

Patterns of VM Design

Patterns of VM Design

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@mraleph

V8
Dart VM

Excelsior JET
v8
Dart VM

Excelsior JET

V8

Dart VM

```
Vector.prototype.length = function () {
    return Math.sqrt(this.x * this.x +
                      this.y * this.y);
};
```

representation
resolution
redundancy

fast \oplus slow

fast \subseteq slow

obj.prop

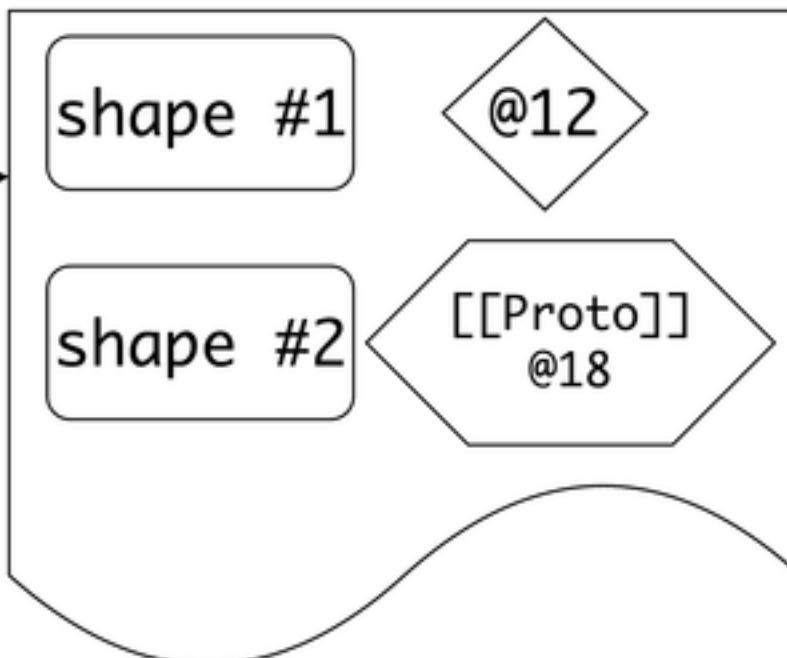
"guess where
property is"

"remember where
property was"

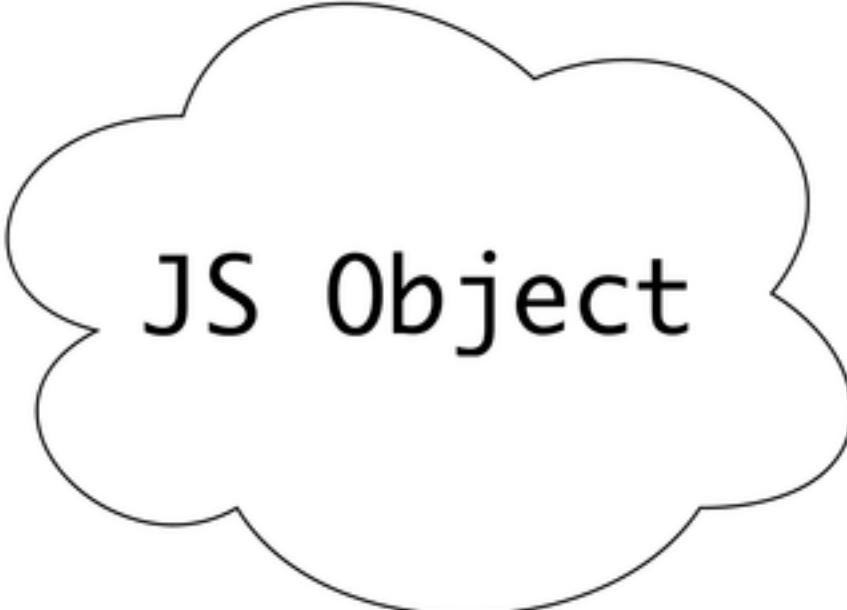
inline caching

obj.prop

Cache
lookup
paths per
lookup site



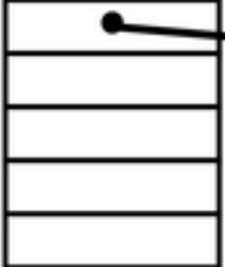
"Shape?!"



JS Object

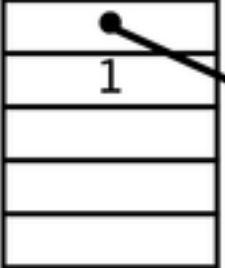
```
function Point(x, y) {  
    this.x = x;  
    this.y = y;  
}  
  
var p1 = new Point(1, 2);  
var p2 = new Point(3, 4);
```

```
function Point(x, y) {  
    this.x = x;  
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}  
  
var p1 = new Point(1, 2);  
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```
function Point(x, y) {  
    this.x = x;  
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}
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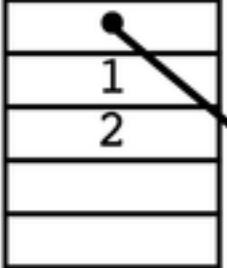
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```



```
function Point(x, y) {  
    this.x = x;  
    this.y = y;  
}  
  
var p1 = new Point(1, 2);  
var p2 = new Point(3, 4);
```

Point {}

Point {x}

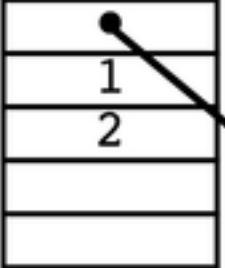


```
function Point(x, y) {  
    this.x = x;  
    this.y = y;  
}  
  
var p1 = new Point(1, 2);  
var p2 = new Point(3, 4);
```

Point {}

Point {x}

Point {x, y}

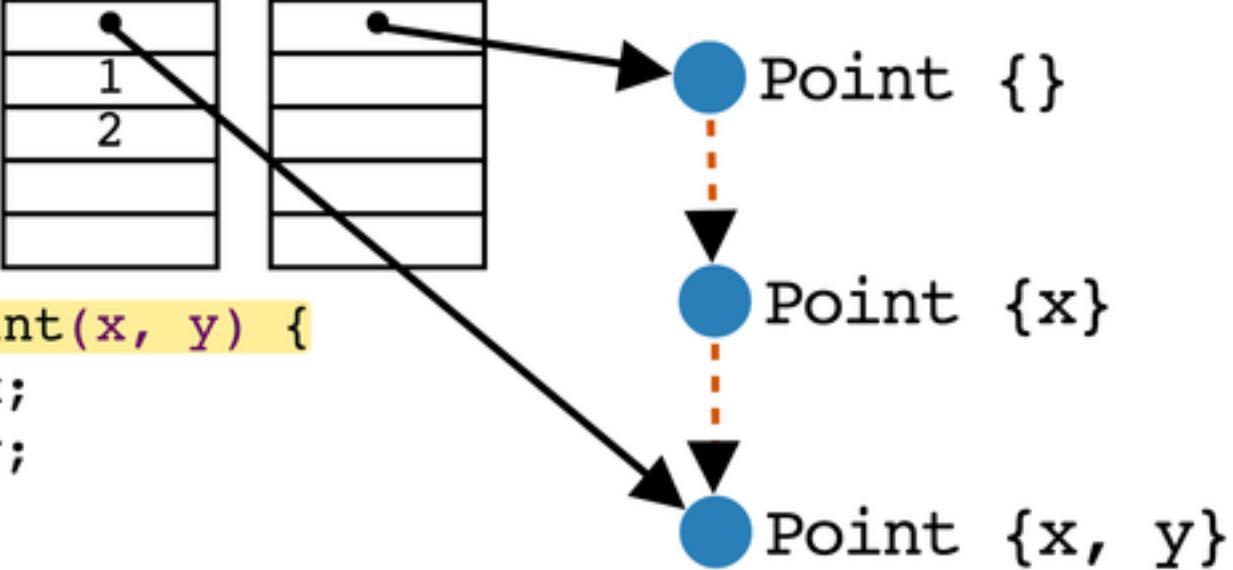


```
function Point(x, y) {  
    this.x = x;  
    this.y = y;  
}  
  
var p1 = new Point(1, 2);  
var p2 = new Point(3, 4);
```

Point {}

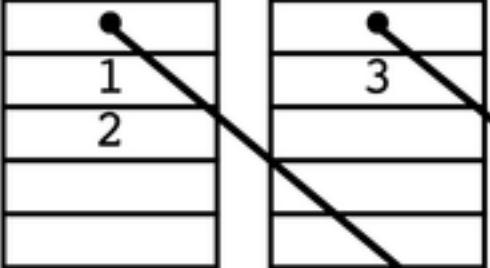
Point {x}

Point {x, y}

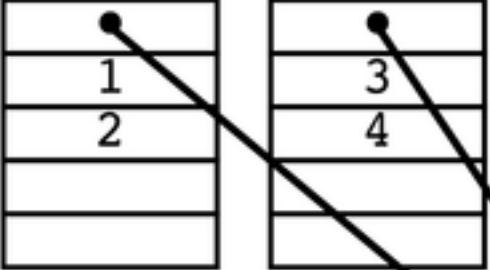


```
function Point(x, y) {
    this.x = x;
    this.y = y;
}

var p1 = new Point(1, 2);
var p2 = new Point(3, 4);
```

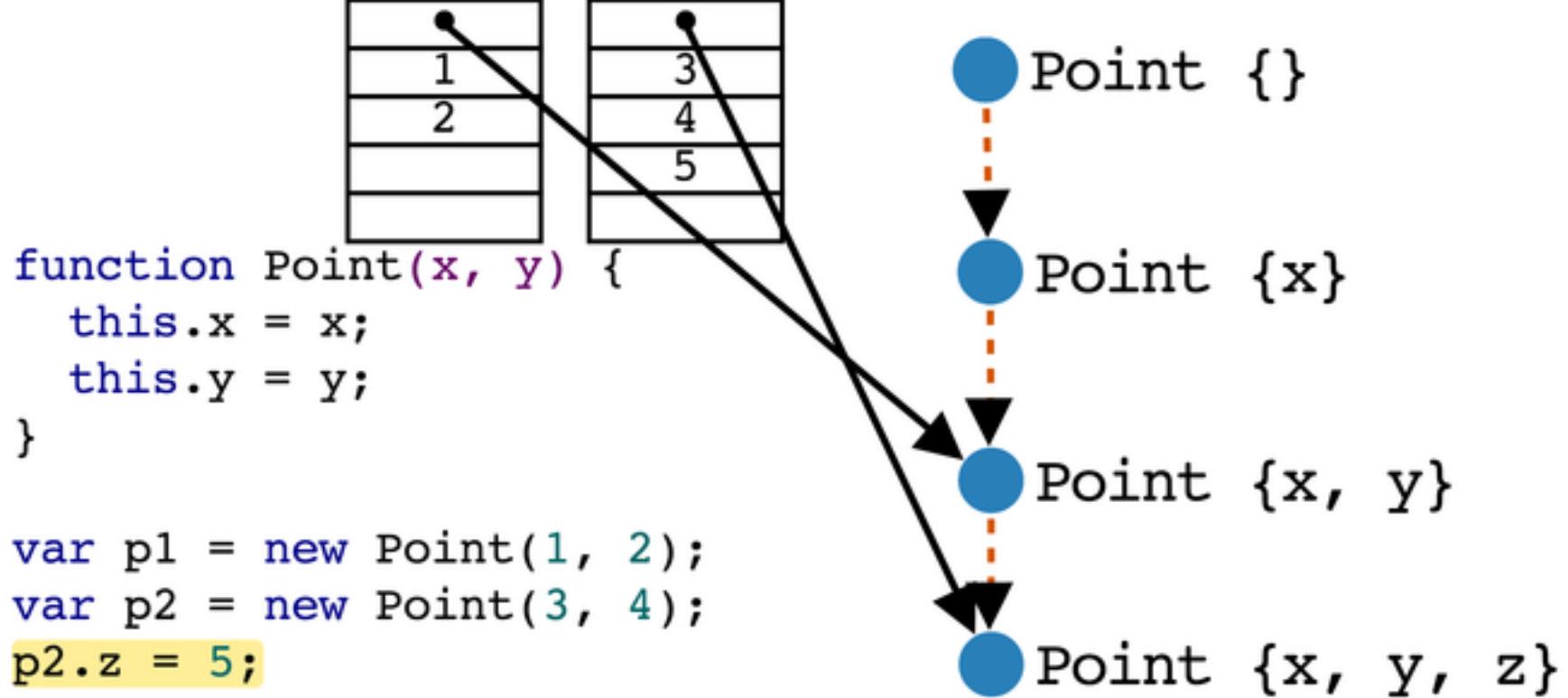


```
function Point(x, y) {  
    this.x = x;  
    this.y = y;  
}  
  
var p1 = new Point(1, 2);  
var p2 = new Point(3, 4);
```



```
function Point(x, y) {  
    this.x = x;  
    this.y = y;  
}  
  
var p1 = new Point(1, 2);  
var p2 = new Point(3, 4);
```

The code defines a constructor function named Point that takes parameters x and y. It uses the this keyword to assign x to this.x and y to this.y. The code then creates two instances of this constructor: p1 with values 1 and 2, and p2 with values 3 and 4.

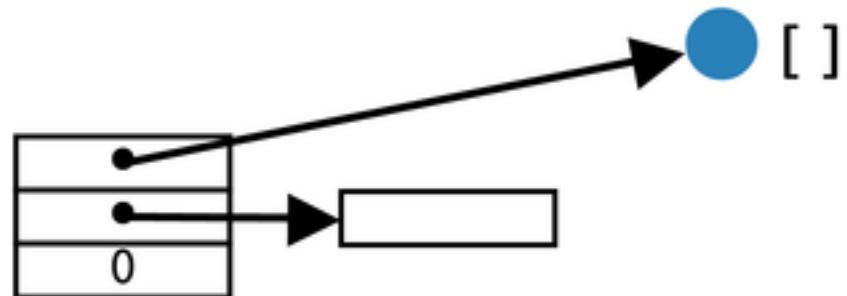


V8 hidden classes
≈ *maps* from Self VM

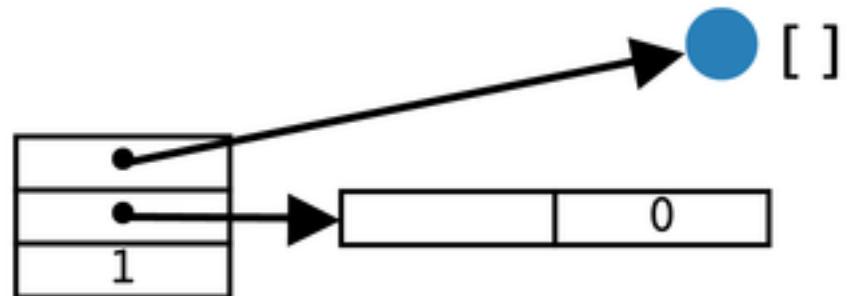
static structure
approximated
dynamically

```
var arr = [ ];
for (var i = 0; i < 101; i++)
    arr[i] = Math.sqrt(i);
```

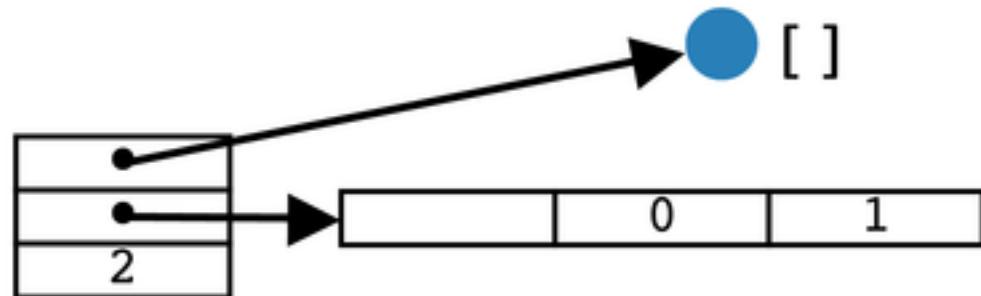
```
var arr = [ ];  
arr[0] = Math.sqrt(0);  
arr[1] = Math.sqrt(1);  
arr[2] = Math.sqrt(2);
```



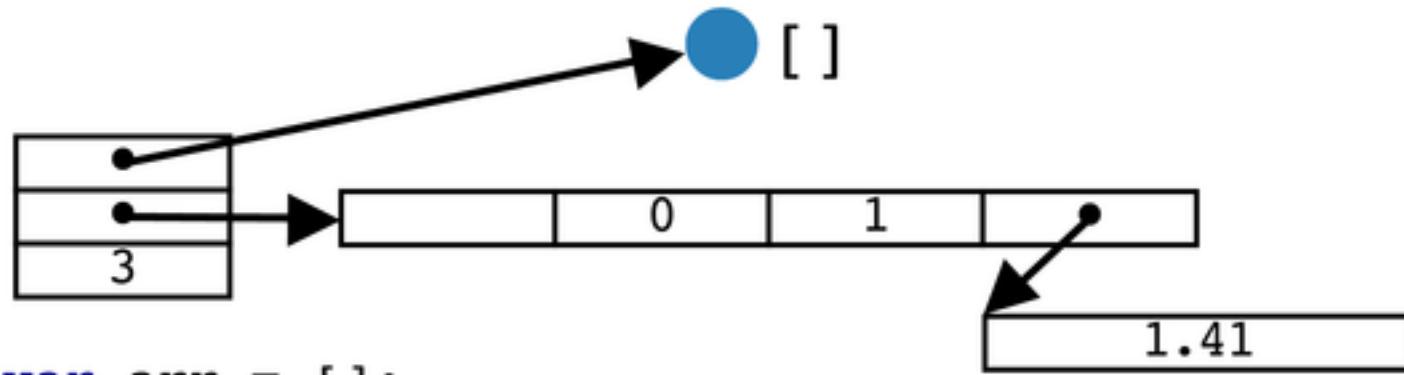
```
var arr = [];
arr[0] = Math.sqrt(0);
arr[1] = Math.sqrt(1);
arr[2] = Math.sqrt(2);
```



```
var arr = [ ];  
arr[0] = Math.sqrt(0);  
arr[1] = Math.sqrt(1);  
arr[2] = Math.sqrt(2);
```



```
var arr = [ ];  
arr[0] = Math.sqrt(0);  
arr[1] = Math.sqrt(1);  
arr[2] = Math.sqrt(2);
```



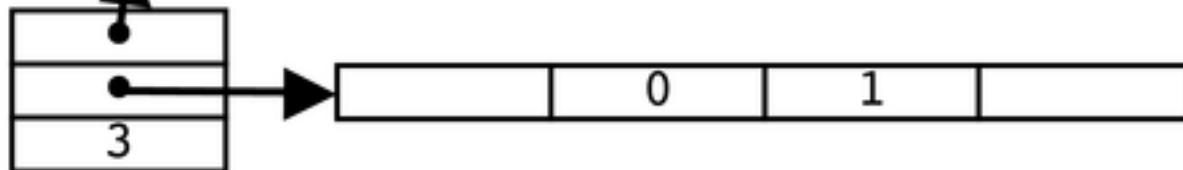
```
var arr = [ ];  
arr[0] = Math.sqrt(0);  
arr[1] = Math.sqrt(1);  
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```



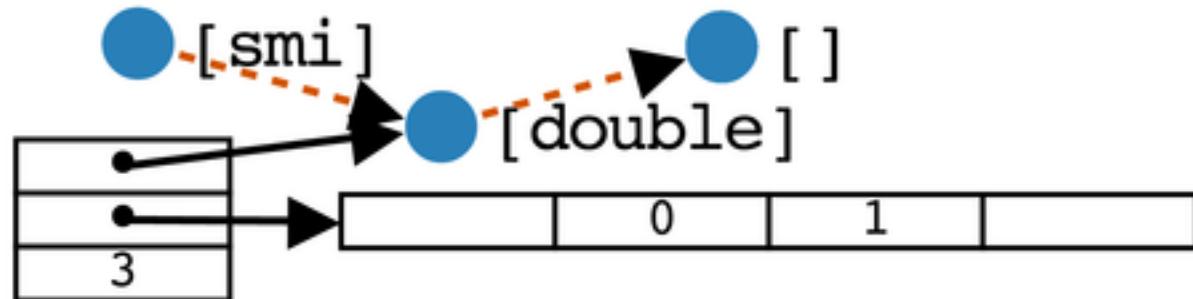
[smi]



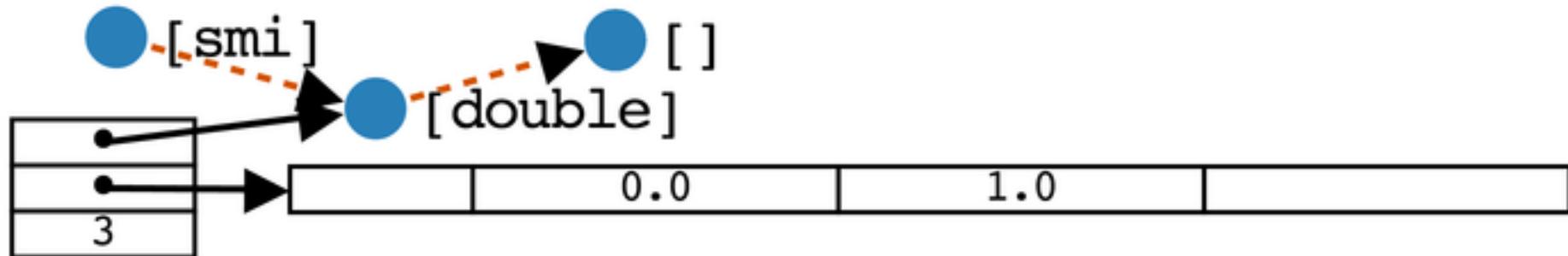
[]



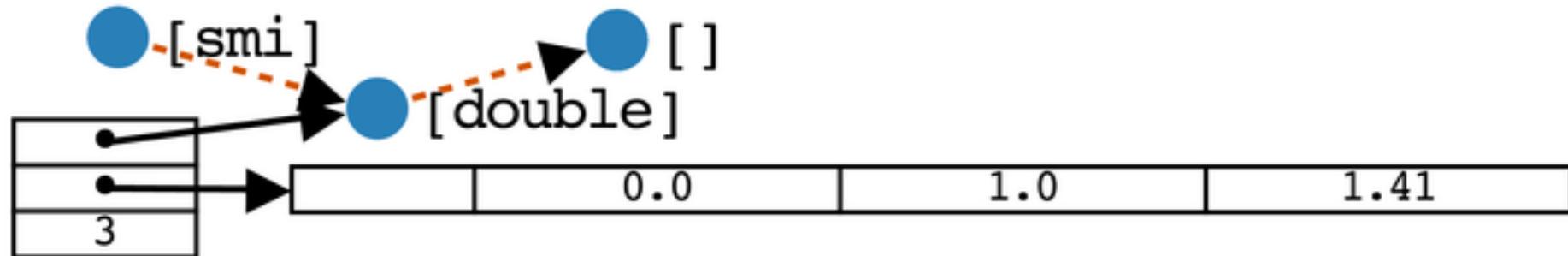
```
var arr = [];
arr[0] = Math.sqrt(0);
arr[1] = Math.sqrt(1);
arr[2] = Math.sqrt(2);
```



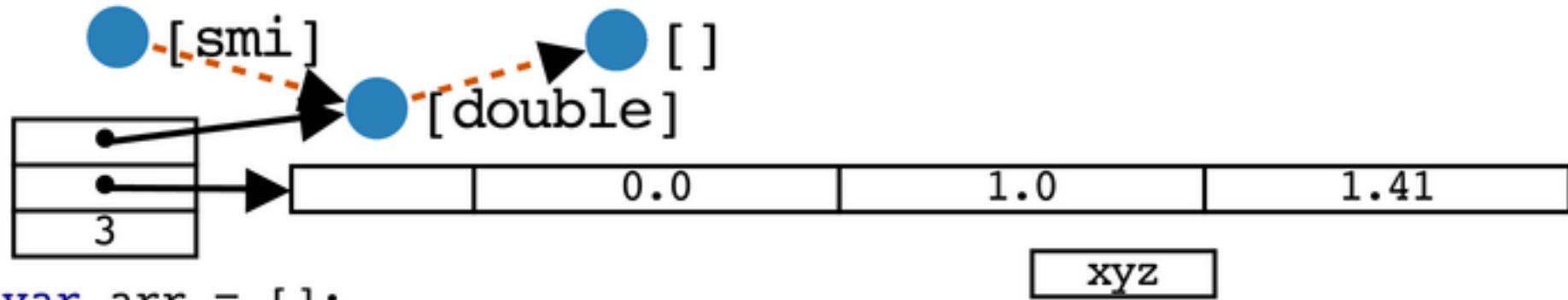
```
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arr[0] = Math.sqrt(0);  
arr[1] = Math.sqrt(1);  
arr[2] = Math.sqrt(2);
```



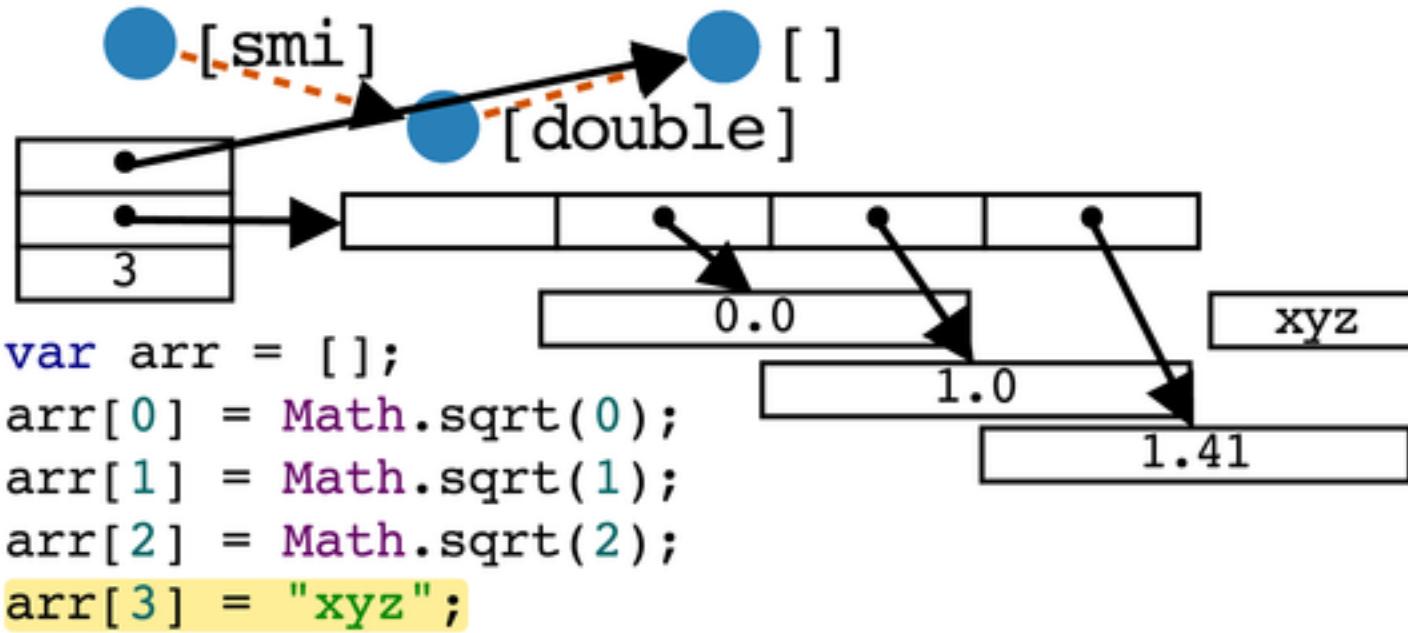
```
var arr = [ ];
arr[0] = Math.sqrt(0);
arr[1] = Math.sqrt(1);
arr[2] = Math.sqrt(2);
```

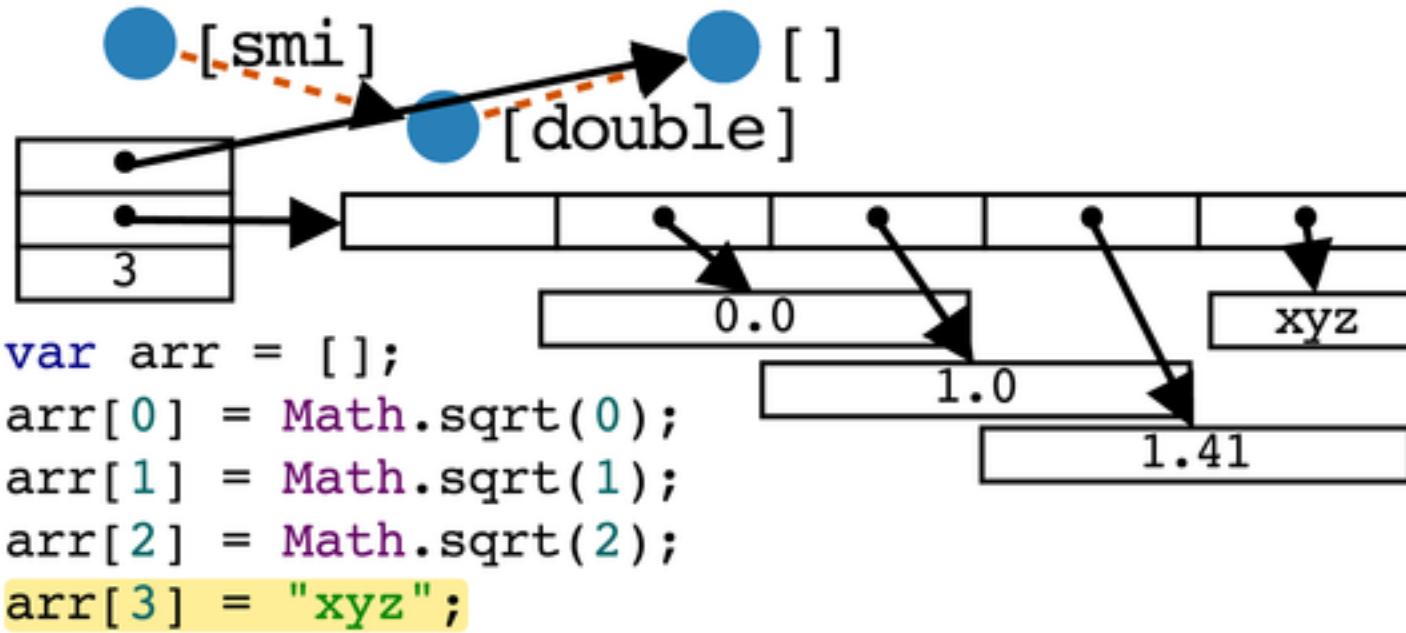


```
var arr = [ ];  
arr[0] = Math.sqrt(0);  
arr[1] = Math.sqrt(1);  
arr[2] = Math.sqrt(2);
```

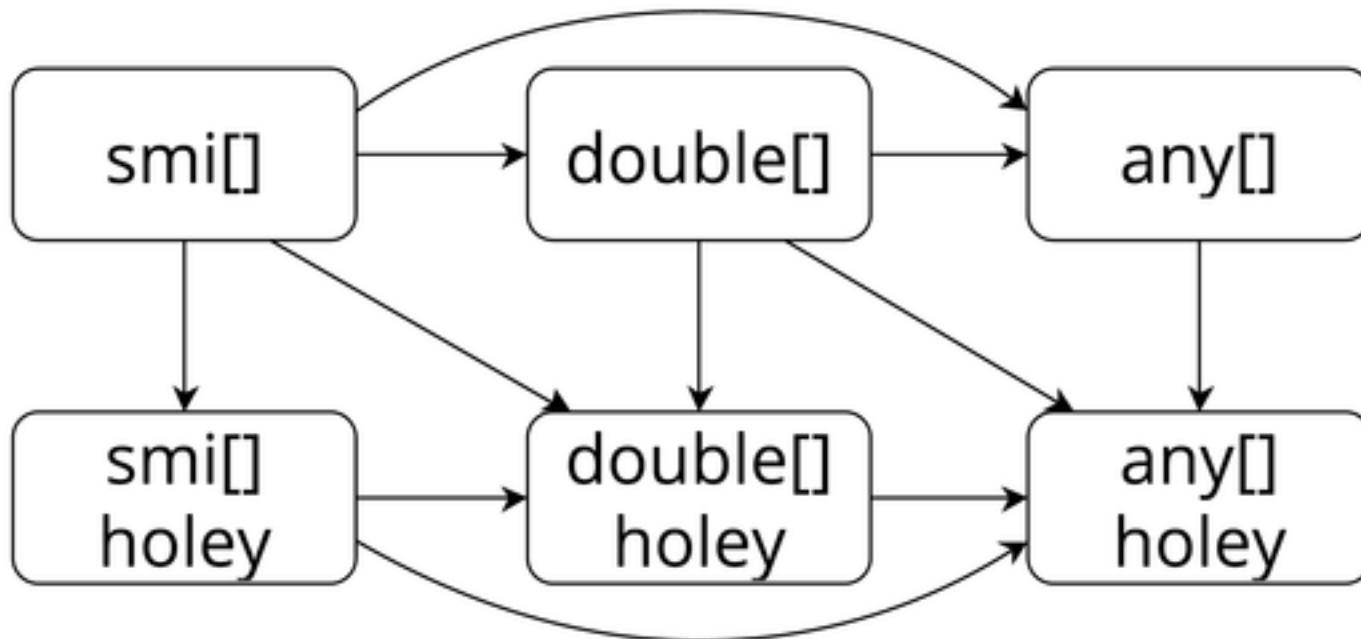


```
var arr = [];
arr[0] = Math.sqrt(0);
arr[1] = Math.sqrt(1);
arr[2] = Math.sqrt(2);
arr[3] = "xyz";
```





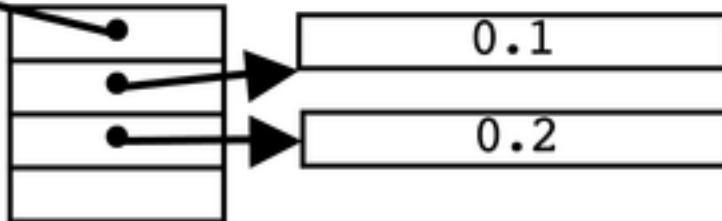
tracking denseness
and unboxing



```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2);  
v.x += 1;  
v.y += 1;
```

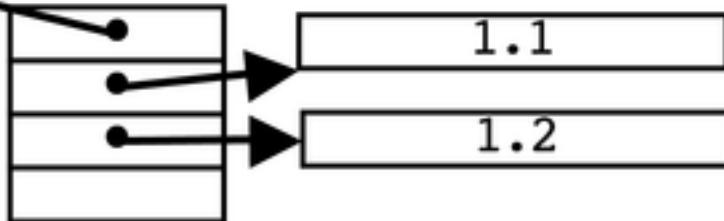
Vec2{x: double, y: double}

```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2);  
v.x += 1;  
v.y += 1;
```



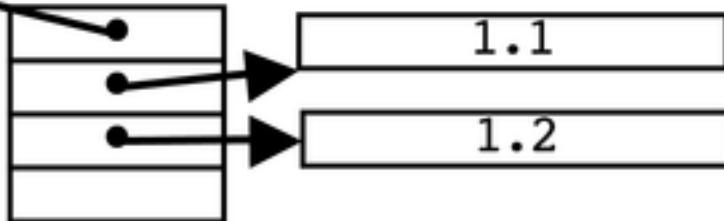
Vec2{x: double, y: double}

```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2);  
v.x += 1;  
v.y += 1;
```



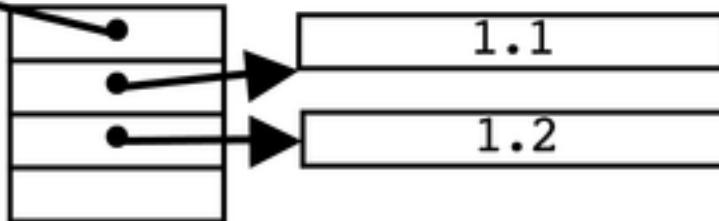
Vec2{x: double, y: double}

```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2);  
v.x += 1; v.y += 1;  
while (true) v.x;
```



Vec2{x: double, y: double}

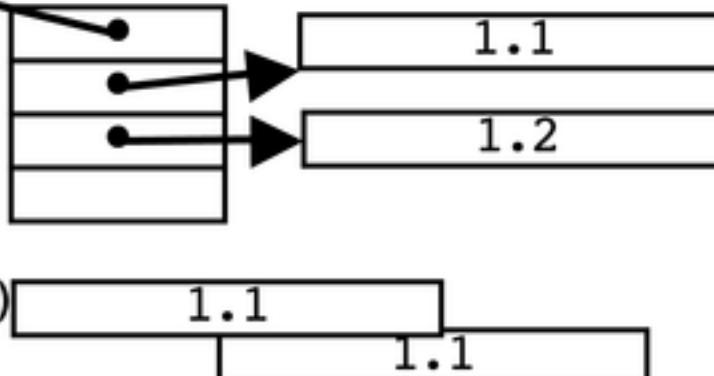
```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2);  
v.x += 1; v.y += 1;  
while (true) v.x;
```



1.1

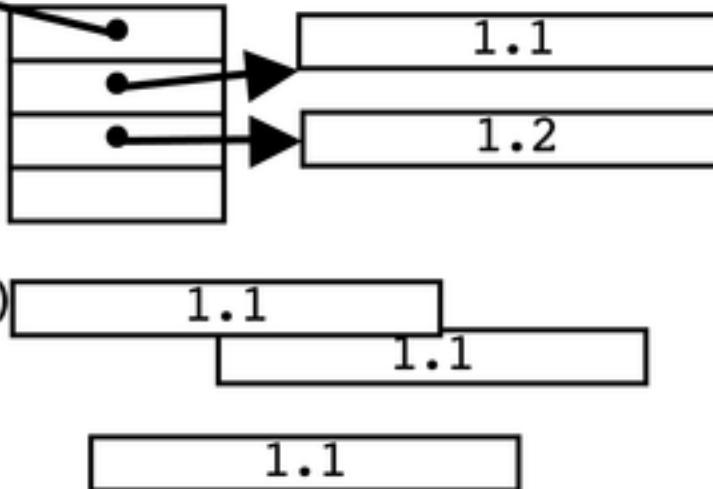
Vec2{x: double, y: double}

```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2)  
v.x += 1; v.y += 1;  
while (true) v.x;
```



Vec2{x: double, y: double}

```
function Vec2(x, y) {  
    this.x = x;  
    this.y = y;  
}  
var v = new Vec2(0.1, 0.2)  
v.x += 1; v.y += 1;  
while (true) v.x;
```



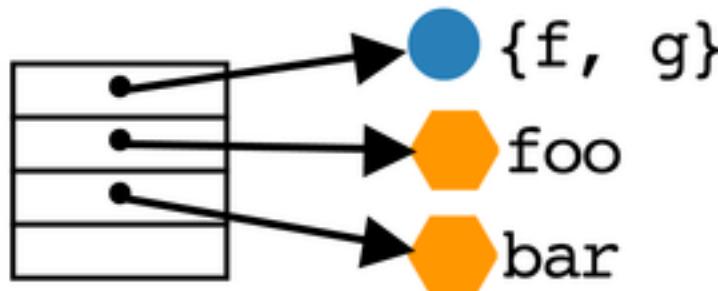
mutable boxes

beneficial if you can read **unboxed**

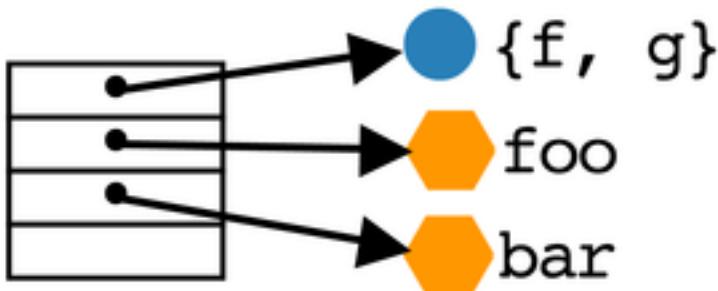
```
function K() { }
K.prototype.f = function foo() { };
K.prototype.g = function bar() { };
```

```
function K() { }
K.prototype.f = function foo() { };
K.prototype.g = function bar() { };
// How hidden class of K.prototype looks like?
```

```
function K() { }
K.prototype.f = function foo() { };
K.prototype.g = function bar() { };
// How hidden class of K.prototype looks like?
```

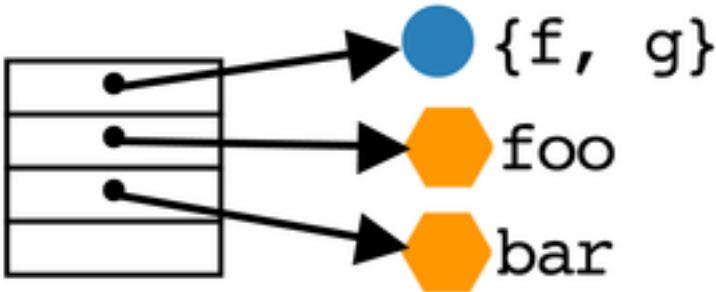


```
function K() { }
K.prototype.f = function foo() { };
K.prototype.g = function bar() { };
// Want it to be more 'class'-like
```

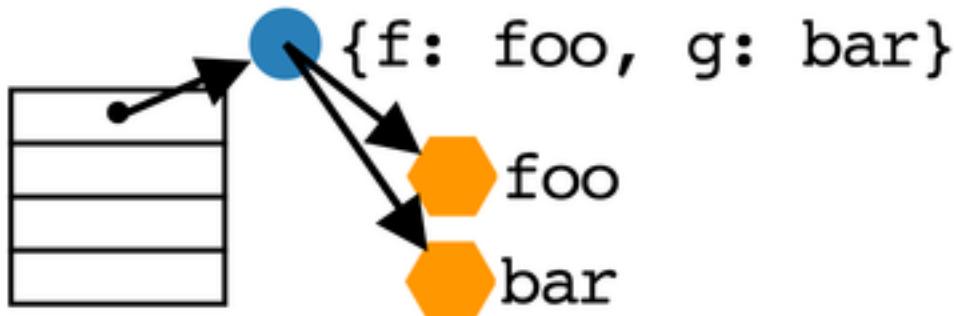


promote functions
to hidden class

```
function K() { }
K.prototype.f = function foo() { };
K.prototype.g = function bar() { };
```



```
function K() { }
K.prototype.f = function foo() { };
K.prototype.g = function bar() { };
// Now it's more like vtbl!
```



"amazing
technology!!1"

"amazing
technology!!1"
has issues

"if there is a metaspace there
is a metaGC problem"

it's still a heuristic

```
var o1 = {};
o1.f = function () { };
var o2 = {};
o2.f = function () { };

for (var i = 0; i < 1e7; i++) o1.f();
for (var i = 0; i < 1e7; i++) o2.f();
```

same hidden class
⇒ same structure

inline caching

In V8

OBJ . PROP

In V8

OBJ_• PROP

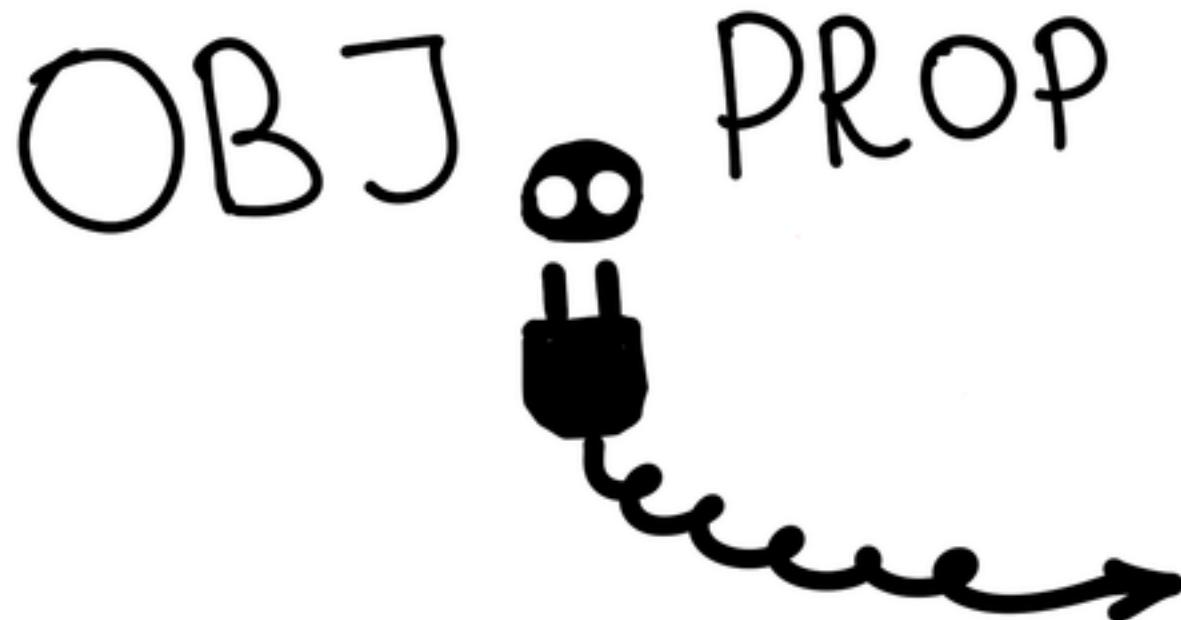
In V8 (American Version)

OBJ_• PROP

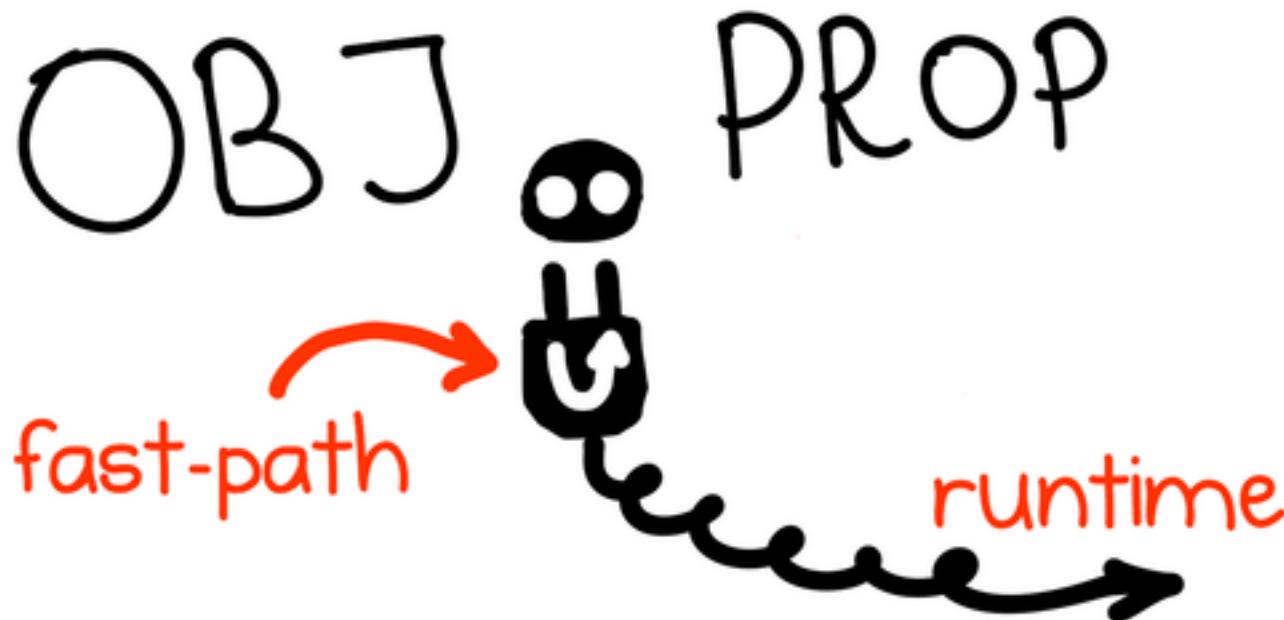
In V8

OBJ_• PROP

In V8



In V8



```
; Compiled code
mov eax, obj
mov ecx, "foo"
call LoadIC_Initialize
```

```
// Runtime system.  
function LoadIC_Initialize(obj, prop) {  
    var lookupResult = obj.lookup(prop);  
    patch(lookupResult.compile());  
    return lookupResult.value;  
}
```

```
// Runtime system.  
function LoadIC_Initialize(obj, prop) {  
    var lookupResult = obj.lookup(prop);  
    patch(lookupResult.compile());  
    return lookupResult.value;  
}
```

```
; Compiled LoadIC Stub
0abcdef:
cmp [eax - 1], klass0
jnz LoadIC_Miss
mov eax, [eax + 11]
ret

; Compiled code
mov eax, obj
mov ecx, "foo"
call 0abcdef ; patched!
```

```
; Compiled LoadIC Stub
0xabcdef:
cmp [eax - 1], klass0
jnz LoadIC_Miss
mov eax, [eax + 11]
ret

; Compiled code
mov eax, obj
mov ecx, "foo"
call 0xabcdef ; patched!
```

```
; Compiled LoadIC Stub
0abcdef:
cmp [eax - 1], klass0
jnz LoadIC_Miss
mov eax, [eax + 11]
ret

; Compiled code
mov eax, obj
mov ecx, "foo"
call 0abcdef ; patched!
```

```
; Compiled LoadIC Stub
0abcdef:
cmp [eax - 1], klass0
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mov eax, [eax + 11]
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; Compiled code
mov eax, obj
mov ecx, "foo"
call 0xabcdef ; patched!
```

```
; Compiled LoadIC Stub
0xabcdef:
cmp [eax - 1], klass0
jnz LoadIC_Miss
mov eax, [eax + 11]
ret

; Compiled code
mov eax, obj
mov ecx, "foo"
call 0xabcdef ; patched!
```

Everything is an IC stub

- property accesses
- element accesses
- method calls
- special method calls
- global variables lookup
- arithmetic operations

In V8

OBJ, PROP



Dart?

Dart?
~~code patching~~

```
function ICStub($data, receiver, ...) {
    var target = $data.get(receiver(klass))
    if (target === null) {
        target = HandleMiss($data, receiver, ...)
    }
    return target(receiver, ...)
}
```

fields access?

everything is a call

```
o.x
```

```
o.get:x()
```

```
o.x = v
```

```
o.set:x(v)
```

everything is a call

```
| o.x
```

```
|   o.get:x()
```

```
| o.x = v
```

```
|   o.set:x(v)
```

uniform = good.

```
Vector.prototype.length = function () {
    return Math.sqrt(this.x * this.x +
                      this.y * this.y);
};
```

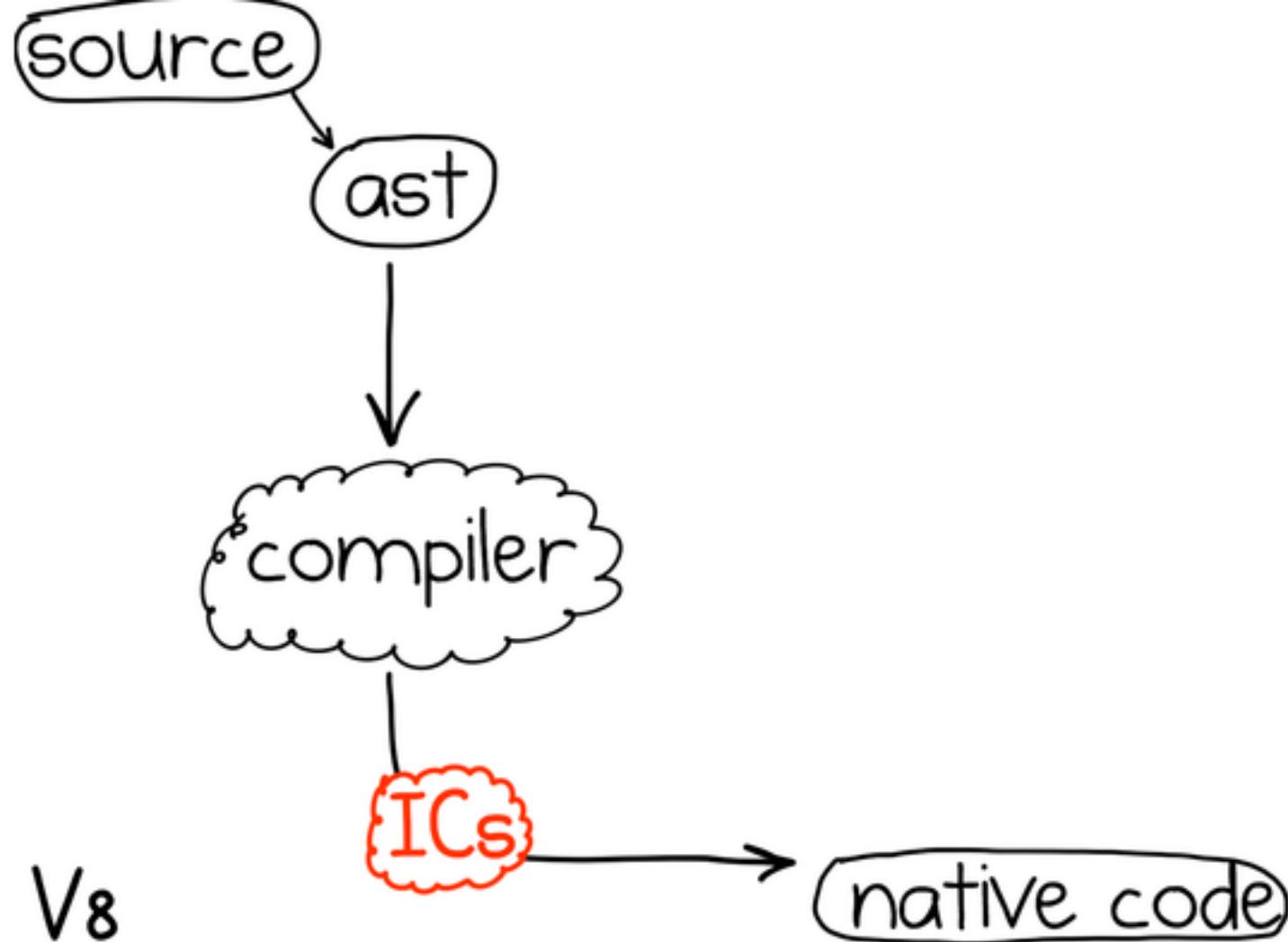
```
Vector.prototype.length = function () {
    return Math.sqrt(this.x * this.x +
                      this.y * this.y);
};
```

$$(\text{fast}_1 \oplus \text{slow}_1) +$$

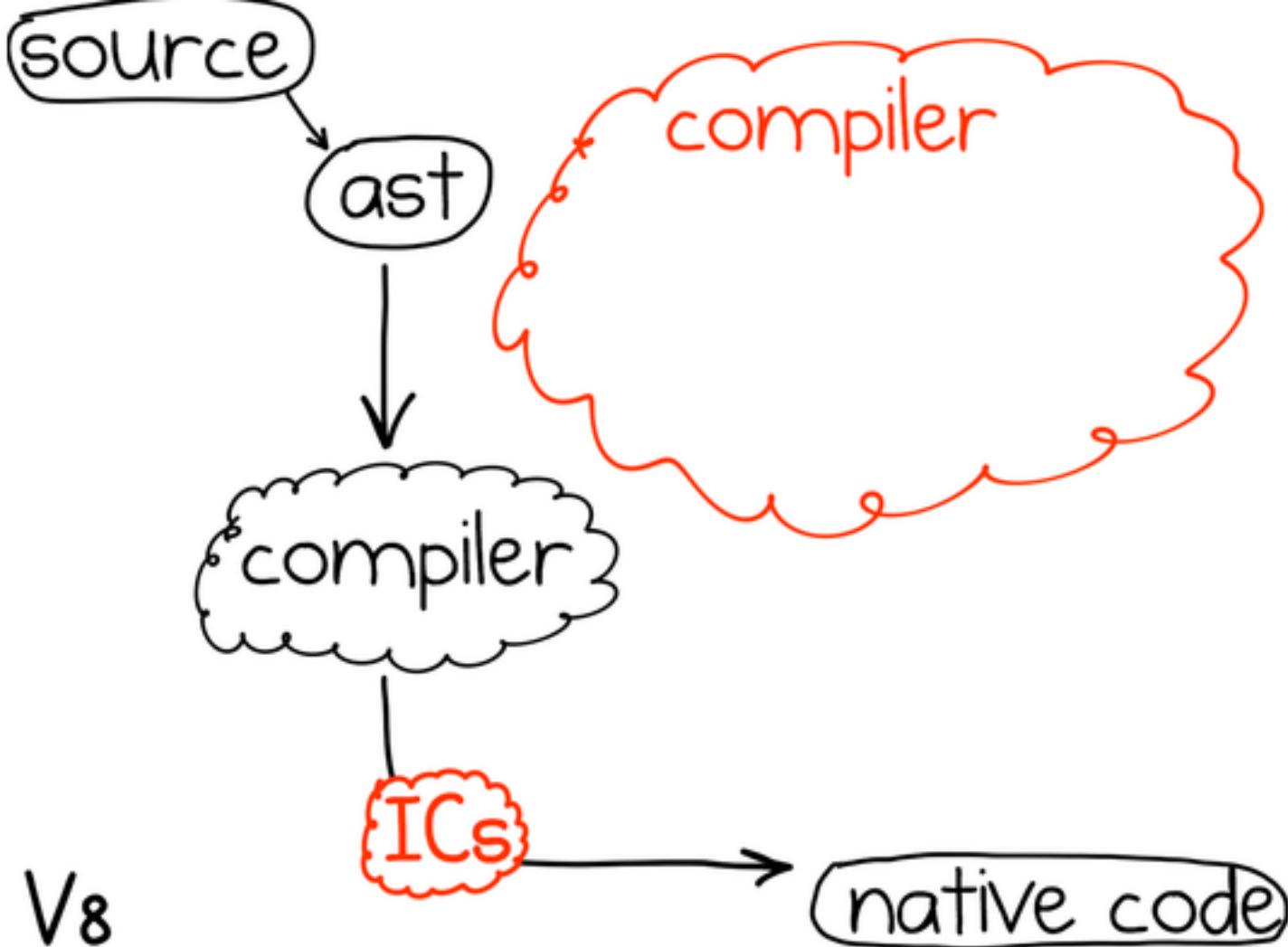
$$(\text{fast}_2 \oplus \text{slow}_2) +$$

$$(\text{fast}_3 \oplus \text{slow}_3) + \dots$$

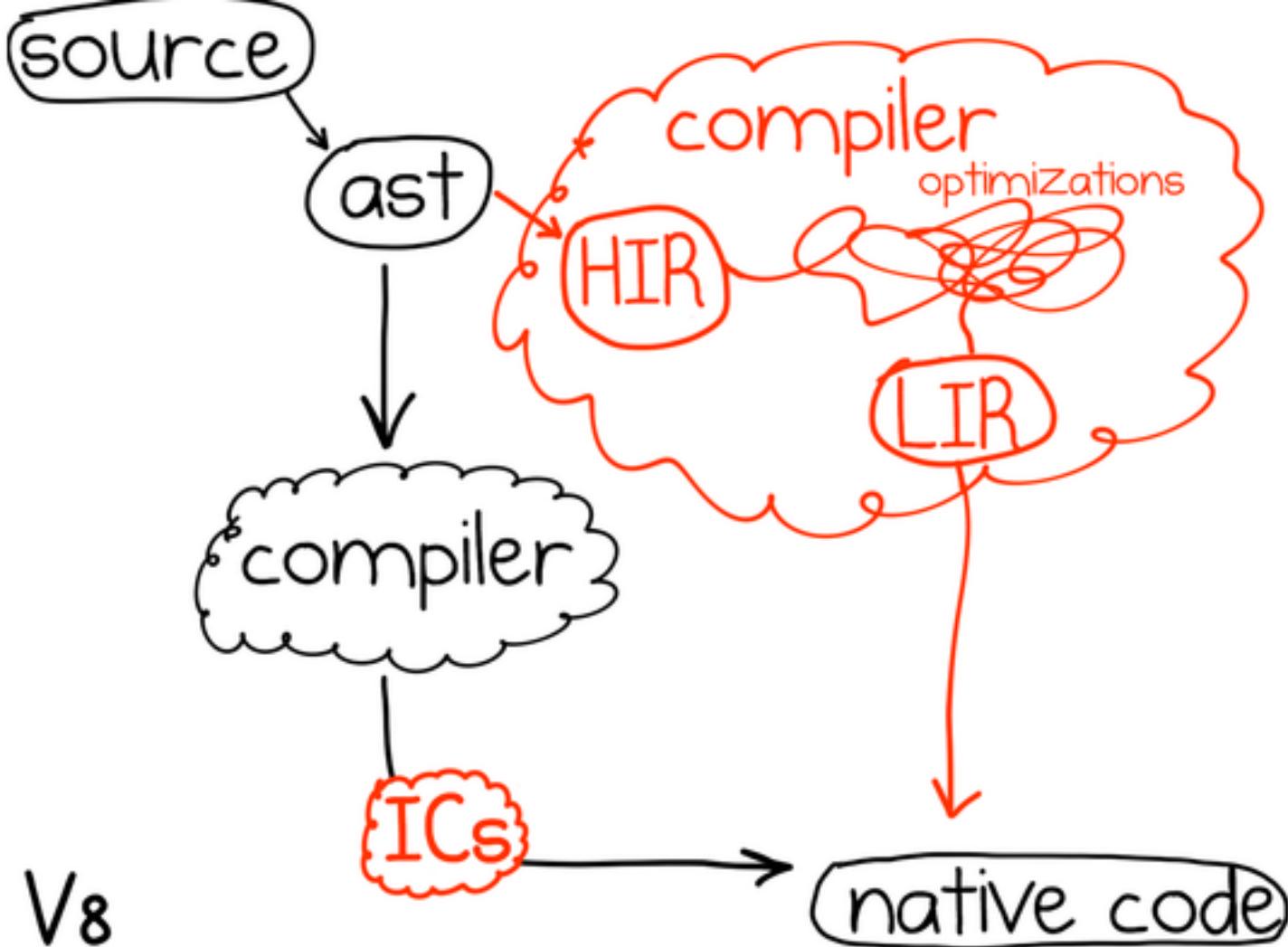
$$(\text{fast}_1 + \text{fast}_2 + \dots) \oplus \text{slow}$$

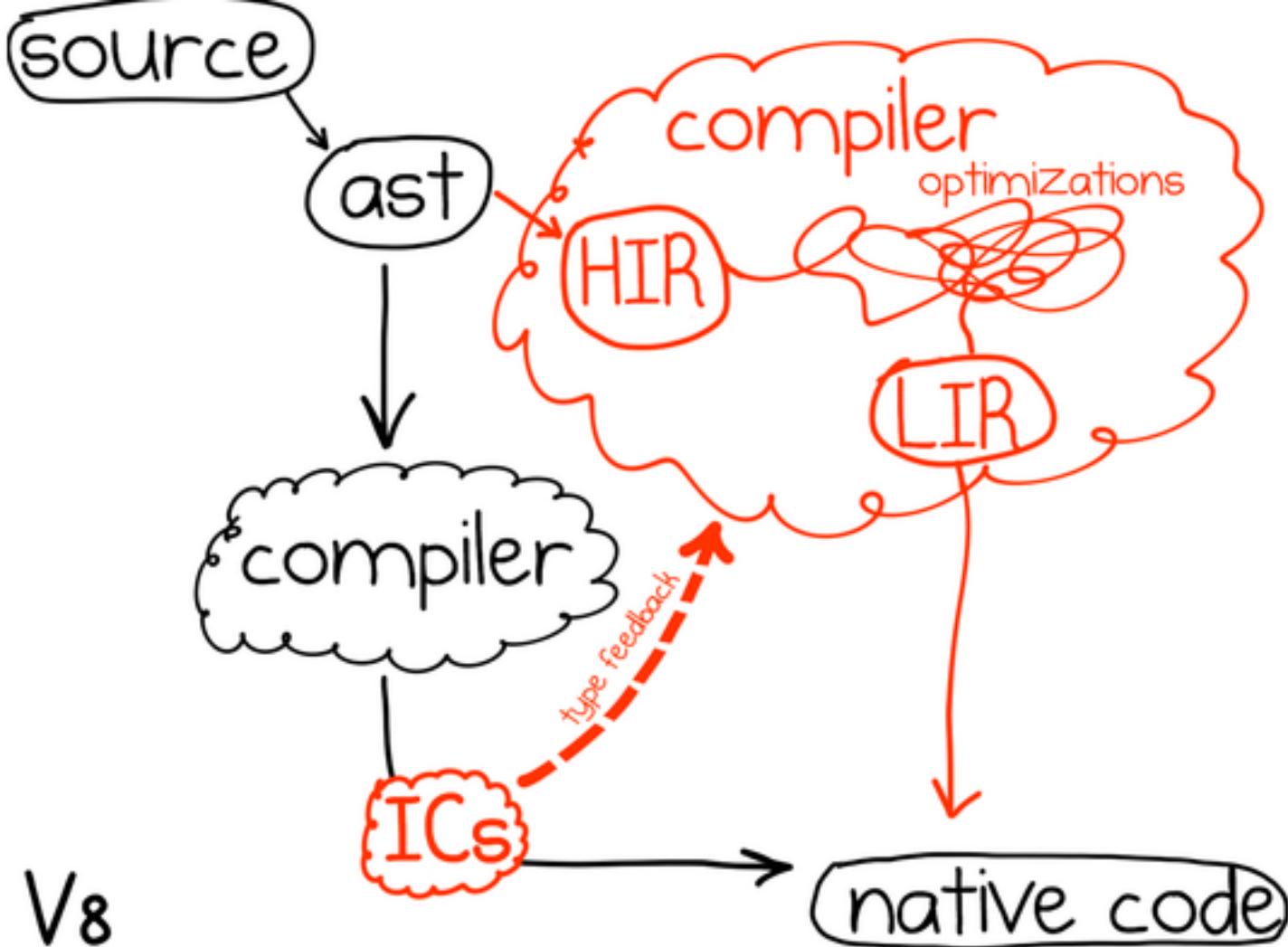


V8

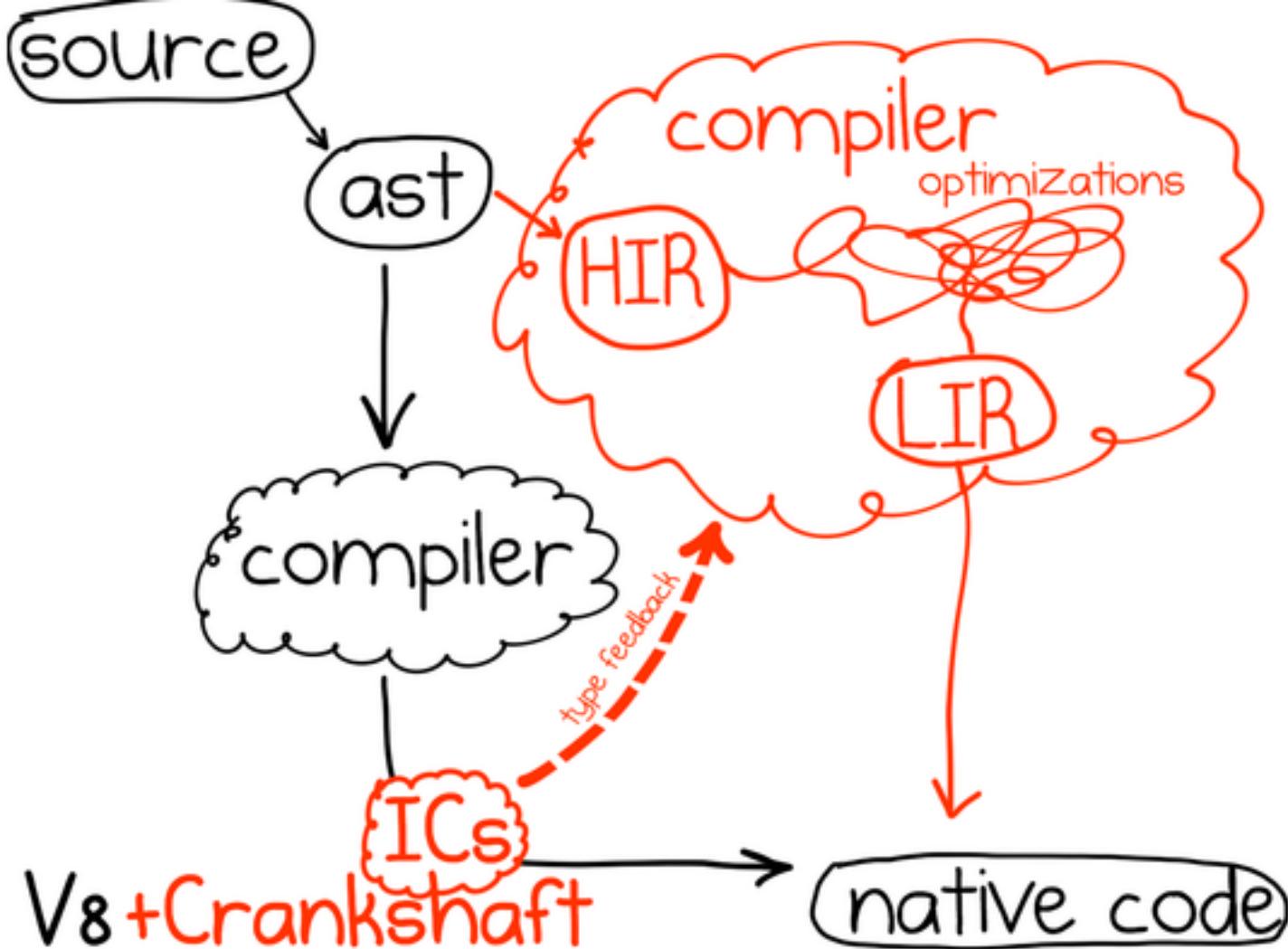


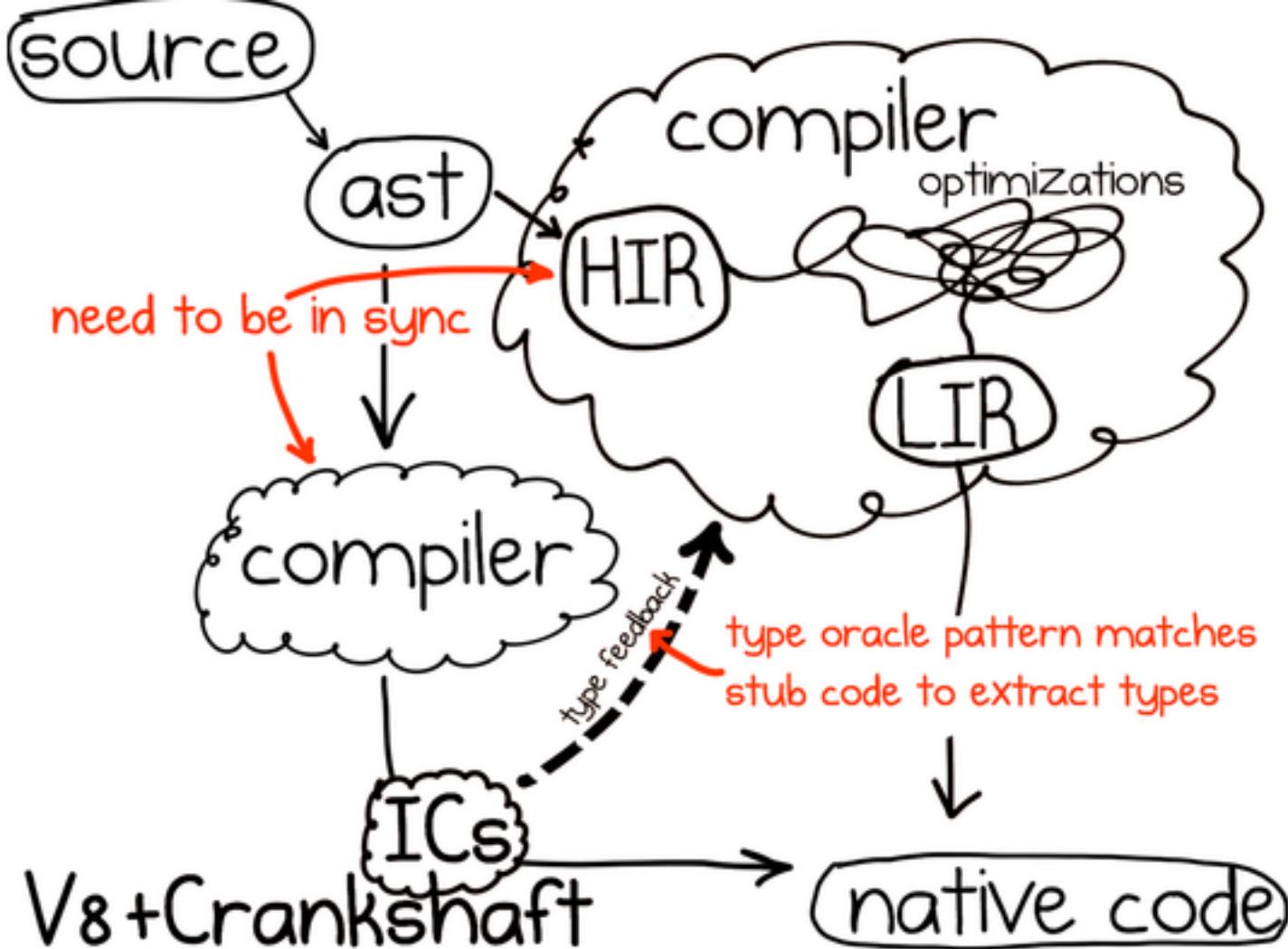
V8





V8





Crankshaft (2010)

1. compile unoptimized code
2. feed hot functions into optimizer
3. speculate types based on IC states
4. apply classic optimizations
5. emit optimized code

Crankshaft (2010)

1. compile unoptimized code
2. feed hot functions into optimizer
3. **speculate** types based on IC states
4. apply classic optimizations
5. emit optimized code

checks in the code
verify speculations

failed check

⇒ jump to unoptimized code

code can **depend** on
assumptions

[e.g. that some prototype chain
does not change]

violated assumption
⇒ deopt dependant code

fast \oplus slow

fast ⊕ slow

"it's a trap"

manual decomposition
maintenance burden

can derive fast-path
(semi)automatically?

"if you have optimizing compiler - use it!"

"if you have optimizing
compiler - use it!"

write IR instead of asm

"if you have optimizing
compiler - use it!"

V8 stubs; Dart VM intrinsics, regexp

runtime speaks
wrong language

user-code?

```
getInferredTypeOf(element) {  
    element = element.implementation;  
    return typeInformations.putIfAbsent(element, () {  
        return new ElementTypeInformation(element, this);  
    });  
}
```

```
getInferredTypeOf(element) {  
    element = element.implementation;  
    return typeInformations.putIfAbsent(element, () {  
        return new ElementTypeInformation(element, this);  
    });  
}
```

```
class _HashMap {
    @jit.AlwaysInline
    putIfAbsent(key, @jit.AlwaysInline ifAbsent) {
        /* ... */
    }
}

@jit.NeverInline
getInferredTypeOf(element) {
    /* ... */
}
```

```
class ListMixin {  
    forEach(f) { /* ... */ }  
}  
  
class List with ListMixin { }  
class Int32List with ListMixin { }  
class Float64List with ListMixin { }
```

```
class ListMixin {
    @jit.ReceiverPolymorphic
    forEach(f) {
        /* ... */
    }
}
```

warmup?

precook fast-paths

"Universal" VM

small yet expressive core language

optimization hints

fast \oplus slow decomposition (guards,
assumptions, deopts)

ability to precompute fast paths at build step

Thank you